# **Angular Position Transducers**



### **Angular Position Transducers**



potentiometric

For measuring angular positions and converting them into electrical signals for teletransmission purposes, either **potentiometric** (see data sheet "precision rotary potentiometer"), **inductive, magnetic, incrementally** or **absolutely coded** angular position transducers can be used according to the particular application.

**Inductive angular position transducers** of the non-contacting type are preferably used on measuring points, which are exposed to extreme vibration or shock or to aggressive atmospheres.

This applies mainly to measurement problems one is confronted with in energy industry and chemical plants, for instance while measuring the actual value of the position of variable speed drives, or of machines in paper-processing and textile industry, while measuring the position of dancer rollers and very frequently in pendulum systems for measuring tilt angles on cranes and excavators.

**Optoelectronic angular position transducers** possess code disks, whose tracks are digitally scanned.

They are high-resolution measuring systems with low temperature coefficient, available in a single- or multi-turn version, outputting analogue or digitally coded signals.

Single-turn transducers are used e. g. in the railway vehicle domain in connection with master controllers or on cranes as slewing ring transmitters.

Multi-turn transducers are preferably used together with rope length measuring systems on hauling plants, bearer cable winches of crane systems or in the field of machine tool engineering for sensing the tool position. **Magnetic angular position transducers** are extremely robust measuring systems completely hermetically encapsulated of two-chamber design with a protection degree of IP 68.

magnetic

optoelectronic

inductive

In shaft exit design e. g. they are used to record the angular position of a permanent magnet mounted on the measuring object.

Transducers of this type are predominately used in commercial vehicles for sensing the position of steering type axles or the angle of the articulated arm of excavators.

Transducers with shaft exit also contain a hermetically encapsulated electronic unit. They are universally used in mechanical engineering exposed to extreme atmospheres in order to record angular positions.

Signals of the single- or multi-turn version are output either analogue as current or voltage signals or digital as CAN open configuration.

Potentiometric angular position transducers contain a high-<br/>reso-Iution resistance element of conductive plastic with a linearity of  $\pm$  0.1 %.

Signals are output either in form of a resistance, current or voltage variation.

## ....System versions



#### Inductive transducer systems (WD)

are available as models of synchro size 20 (series 620) and synchro size 23 (series 1023). They contain a differential inductor designed in form of a ring winding with a non-contact tapping. The electrical output signals representing zero and final value of the mechanical drive shaft angle are available within a broad range of limits via trimming potentiometers of the incorporated or separate electronics.

For use in explosive installations, transducer systems as well as electronic components are available with a degree of protection EEx and Exd with ATEX approval.



#### Potentiometric transducer systems (PK)

are also available in synchro sizes 20 and 23. They contain an incorporated signal converter with current or voltage signal output.





#### Magnetic transducer systems (MR and MH)

are available as models of synchro sizes 9, 13, 20 and 23. They are fully enclosed in an aluminium casing of two chamber design and contain a permanent magnet with a high-precision angular encoder.

Signals are output either analogue, e. g. with 4 - 20 mA, or digitally coded (CAN open standard).

Output signal of transducers with analogue output can be programmed via rear keys of transducer to the respective measuring range.

For safety-relevant applications these systems are also available in redundant version according to IEC 61508 (SIL).

#### **Optoelectronic transducer systems (XI and XA)**

are available as models of synchro size 23 in incremental of absolutely coded design.

Incremental systems convert the angle to be measured into a proportional number of pulses, appearing in two tracks A and B with an offset of 90° for identification of direction. Absolutely coded systems are available as single- or multi-turn encoders.

They contain a gray-coded rotating disk whose 12 concentric tracks are optically scanned by infrared diodes and phototransistors. Signals are output parallel via NPN or PNP transistors or analogue via a digital-to-analogue converter with current output 4 - 20 mA. All transducers can also be supplied with field bus interface CAN open standard and in user-specific data format respectively.

# ....Specifications

System versions	Magnetic systems							2-fold system	
Models		12 Million	<b>()</b>						
Series	МН	609	MH 613		MH 620	MR 1023		MR 1023 ext	Xi / MR 1023
Single-turn / multi-turn	single-turn	multi-turn	single-turn	multi-turn	single-turn	single-turn multi-turn		single-turn	single-turn
Synchro size	e 9		13		20	20		special size	23
Casing - ø	22.2	22.2 mm 36.5 mm		5 mm	50.8 mm	60 mm		60 mm	60 mm
Shaft - ø	6 r	nm	6 mm		6 mm	6 / 10 mm		external magnet	6 / 10 mm
Dimensional sketch page 6/7		1 2		2	5	7 and 8		6	7
Angle of rotation max.	360°	1080°	360°	5760°	360°	360° 23040°		360°	360°
Revolution max.	1	3	1	16	1	1	64	1	1
Voltage output	0.5 -	0.5 - 4.5 V							
Current output			4 - 20 mA		1 x 4 - 20 mA	4 - 20 mA		4 - 20 mA	
Pulse output									
Bus output						CANopen			
Redundant electronics					2 x 4 - 20 mA				4 - 20 mA / 720 pulses
Signal adjustment via	fixed al	ignment	keys		cable	keys or CAN-Bus		fixed alignment	fixed alignment
Linearity	± 0.5 %	±1%	± 0	.3 %	± 0.2 %	± 0.2 %		± 0.2 %	± 0.2 %
Resolution	12	bit	12 bit	16 bit	12 bit	14 bit		14 bit	14 bit / 720 pulses
Supply	5 V	DC	24 V DC		1 x or 2 x 24 V DC	24 V DC		24 V DC	2 x 24 V DC
Current consumption	< 8	0 mA	< 80 mA		< 80 mA	< 80 mA		< 80 mA	< 80 mA
IP code of casing up to	IP	67	IP 65		IP 67	IP68		IP68	IP68
Connection	strand	anded wire solder-type terminals		cable	plug / cable		plug / cable	plug / cable	
Weight	10	0 g	10	0 g	200 g	400 g 400 g		400 g	500 g
Approval								TÜV	
Root of FSG ident #	1130Z01	1140Z01	2740Z01	2750Z01	2845Z01	5750Z02	5755Z02	5850Z01	5770Z02

#### **General data**

Casing material	alu, anodized, partly vanished, special version: saline-resistant coating HART-COAT
Shaft material	stainless steel
Shaft bearing	ball bearing
Temperature range	-30°C up to +70°C, other ranges on request
Test voltage	500 V, 50 Hz, 1 min
Immunity standard	EN 50 082-2
Emission standard	EN 50 081-1
Shock	50 g, 6 ms
Vibration	4 g Sinus 5 - 100 Hz
Current output	$R_L \leqq 600_\Omega$ 3 wire system, 2 and 4 wire system on request
Voltage output	$R_L \ge 10 k_\Omega$ 4 wire system
Supply voltage	18 - 33 V DC, other supply on request

System versions	optoelectronic systems				inductive	systems	potentiometric systems	
Models				C C C C C C C C C C C C C C C C C C C				
Series	XA 1	1023	Xi 1023	WD 620*		WD 1023*	PK 620	PK 1023
Single-turn / multi-turn	single-turn multi-turn		incremental	single-turn		single-turn	single-turn	single-turn
Synchro size	23		23	20		23	20	23
Casing - ø	60 mm		60 mm	50.8 mm		60 mm	50.8 mm	60 mm
Shaft - ø	6 / 10 mm		6 / 10 mm	6 mm		6 / 10 mm	6 mm	6 / 10 mm
Dimensional sketch page 6/7	7.	/ 8	7	3	4	7	4	7
Angle of rotation max.	360° 23040°		n x 360°	360°		360°	355°	355°
Revolution max.	1	64 continuous		1		1	1	1
Voltage output				external	0 - 10 V	0 - 10 V	0 - 10 V	0 - 10 V
Current output	4 - 20 mA			see page 8	4 - 20 mA	4 - 20 mA	4 - 20 mA	4 - 20 mA
Pulse output			A, B and zero track					
Bus output	CANopen							
Redundant electronics								
Signal adjustment via	fixed alignment		fixed alignment	ext.electronic	trimmer	trimmer	trimmer	trimmer
Linearity	± 0,2 %			± 0.5 %		± 0.5 %	± 0.1 %	± 0.1 %
Resolution	12 bit	16 bit	1800 pulses / 360°	c	ø	×	00 C	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
Supply	24 V DC		24 V DC	ext.electronic	24 V DC	24 V DC	24 V DC	24 V DC
Current consumption	< 80 mA		< 50 mA	< 60 mA		60 mA	60 mA	60 mA
IP code of casing up to	IP67		IP67	IP30		IP67	IP 30	IP 67
Connection	plug		plug	solder-type terminals		plug	solder-type terminals	plug
Weight	400 g		400 g	60g 120 g		400 g	120 g	400 g
Approval	<u> </u>			Atex		Atex		
Root of FSG ident #	5740Z02	5730Z02	5760Z02	2810Z50	9252Z10	5700Z02	1572Z02	5710Z02

 $^{\star}$  series WD also available in intrinsically safe version, see page 8



Termina	l connecti	ng	plan	color of stranded wire or cable	solder-type terminals
cable / stran	ded wire supply	Us	+	Green	5
		0 V		Brown	4
V- or mA	output		+	Yellow	25
			-	White	24
plug	supply	Us	+	6	$\bigcirc \bigcirc \bigcirc$
7-poles		0 V		1	30 04
V- or mA	output		+	2	10706
			-	4	0
plug	supply	Us	+	2	$\bigcirc \bigcirc \bigcirc$
5-poles		0 V		3	2 34
	CAN output	Low	/	5	°1 5°
		Higl	h	4	$\odot$

**Switching version** 



# ...Models



















### ... Characteristics of separate components







### Signal converter

#### Type WEVI ... / K16

#### Signal converter

#### Type WEVI ... EEX / K16

### Power supply with signal isolator

Type NBW EEX	( / K16
Input:	4 - 20 mA intrinsically safe
Output:	4 - 20 mA electrically isolated from input $R_L \leq \! 450{\rm cm}$
Supply:	230 V AC
Type of protection:	CE0102 EXII(2)G[EExib]IIc; PTB-Nr. 04 ATEX 2050
Weight:	300 g
Root of FSG ident #:	8249Z02

#### **Protective casing**

Pressure-tight protection for mounting of all angular position transducers

Type ... / GS120 EEXIP code of casing:IP65Type of protection:EXII 2G EEX de IIc T5PTB-Nr. 03 ATEX 1062PTB-Nr. 03 ATEX 1062Weight:5.000 gRoot of FSG ident #: 1785Z02

<mark>(Ex</mark>

Further protective casings are available which can partly be equipped with gearings and limit switches, degree of protection up to IP 68 for mounting in installations with increased mechanical and climatic stress (see data sheet "protective casings").





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