

## Compact, optical

## Sendix F3668 / F3688 (Shaft / Hollow shaft)

**CANopen** 



The Sendix F36 multiturn is an optical multiturn encoder in miniature format, without gears and with 100% insensitivity to magnetic fields. With a size of just 36 x 42 mm it offers a shaft or a blind hollow shaft of up to 10 mm.





Recipients of the MessTec & Sensor Master 2010 Award and the Golden Mousetrap Award 2009.















CANOPER









High rotational

Temperature

High IP value

High shaft load capacity

Shock / vibration resistant

Magnetic field

Short-circuit

Reverse polarity

Optical sensor

Seawater-resistant version on request

# Reliable and magnetically insensitive

- Electronic multiturn with Intelligent Scan Technology™ 100 % magnetic-field resistant
- Sturdy bearing construction in Safety Lock™ Design for resistance against vibration and installation errors
- · Reduced number of components ensures magnetic insensitivity
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40°C up to +85°C

## **Up-to-the-minute Fieldbus performance**

- CANopen with current encoder profile
- · LSS services for configuration of the node address and baud rate
- · Variable PDO mapping in the memory

# Order code **Shaft version**

a Flange, ø 36 mm

1 = clamping flange, IP67 2 = synchro flange, IP67

3 = clamping flange, IP65

4 = synchro flange, IP65

8.F3668

Shaft (ø x L), with flat

2 = Ø 6,35 (1/4") x 12,5 mm

4 = Ø 9,5 x 15,875 mm (3/8" x 5/8")

X X 2 X **9 0 0** 

 $1 = \emptyset 6 \times 12,5 \text{ mm}$ 

 $3 = \emptyset 8 \times 15 \text{ mm}$ 

 $5 = \emptyset 10 \times 20 \text{ mm}$ 

X|X|2|X|**a b e d** 

21

2

 $\Omega$ ts. up to 50 pcs. of these types generally have a delivery time of 15 working days

C Interface / Power supply

Type of connection 1 = cable, tangential (1 m PUR)

3 = cable, tangential (5 m PUR)

e Fieldbus profile

21 = CANopen Encoder profile DS406 V3.2

2 = CANopen DS301 V4.02 / 10 ... 30 V DC

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a ma



optional on request - Ex 2/22

- seawater-resistant

- special cable length

## Order code **Hollow shaft**

8.F3688

 $5 = \emptyset 6 \text{ mm}$  $6 = \emptyset 6.35 \text{ mm } (1/4")$ 

 $7 = \emptyset 8 mm$ 

1 2 21

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Ots. up to 50 pcs. of these types generally have a delivery time of 15 working days



a Flange, ø 36 mm, IP65 1 = with torque stop, short

3 = with torque stop, long

2 = with stator coupling

Blind hollow shaft  $4 = \emptyset 10 \text{ mm}$ 

2 = CANopen DS301 V4.02 / 10 ... 30 V DC

Type of connection 1 = cable, tangential (1 m PUR)

3 = cable, tangential (5 m PUR)

© Interface / Power supply

e Fieldbus profile

optional on request

- Ex 2/22

- seawater-resistant

- special cable length

21 = CANopen Encoder profile DS406 V3.2



- DVD with Ezturn® software

#### Compact, optical Sendix F3668 / F3688 (Shaft / Hollow shaft) **CANopen** Mounting accessory for shaft encoders 8.0000.1101.0808 Coupling Bellows coupling ø 19 mm for shaft 6 mm Mounting accessory for hollow shaft encoders Cylindrical pin, long 8.0010.4700.0000 With fixing thread for torque stops Connection Technology Connector, self-assembly (straight) M12 8.0000.5111.0000 **Programming set** including: - Interface converter USB-CAN 8.0010.9000.0015 Minimum System Requirements: - Connection cable from interface converter to encoder Operating system: Windows XP SP3 or higher - Power supply 90 ... 250 V AC Win7 in preparation

Processor: RAM:

Required disk space: 500 MB

Further accessories can be found in the Accessories section or in the Accessories area of our website at: www.kuebler.com/accessories.

Additional connectors can be found in the Connection Technology section or in the Connection Technology area of our website at: www.kuebler.com/connection\_technology.

Mechanical characteristics			
Maximum speed Shaft- or blind hollow shaft version without shaft seal (IP65)		12 000 min <sup>-1</sup> 10 000 min <sup>-1</sup> (continuous op.)	
Shaft version (IP67) or hollow shaft version (IP65) with shaft seal		10 000 min <sup>-1</sup> 8 000 min <sup>-1</sup> (continuous op.)	
Starting torque	without shaft seal with shaft seal (IP67)	< 0.007 Nm < 0.01 Nm	
Shaft load capacity	radial axial	40 N 20 N	
Weight		ca. 0.2 kg	
Protection to EN 60 529	housing side shaft side	IP 67 IP 65 (solid shaft version opt. IP67)	
EX approval for hazardou	optional Zone 2 and 22		
Working temperature range		-40°C +85°C	
Materials	shaft / hollow shaft flange housing cable	stainless steel aluminium zinc die-cast PUR	
Shock resistance acc. to EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms	
Vibration resistance acc. to EN 60068-2-6		100 m/s², 55 2000 Hz	

Diagnostic LED (two-colour, red/green)				
LED ON or blinking		Error display Status display		

General electrical characteristics	
Supply voltage	10 30 V DC
Current consumption (no load)	max. 80 mA
Reverse connection of the supply voltage (U <sub>B</sub> )	yes
RoHS compliant acc. to	EU guideline 2002/95/EG
CE compliant acc. to	EN 61000-6-2, EN 61000-6-4, and EN 61000-6-3

1 GHz

512 MB

Interface characteristics CANopen		
Resolution Singleturn	1 65536 (16 bit), scaleable:: 1 65536	
Default value Singleturn	8192 (13 bit)	
Total resolution	1 4.294.967.296 (32 bit) Default: 25 bit	
Code	Binary	
Interface	CAN High-Speed according to ISO 11898, Basic- and Full-CAN, CAN Specification 2.0 B	
Protocol	CANopen profile DS406 V3.2 with manufacturer-specific add-ons LSS-Service DS305 V2.0	
Baud rate	10 1000 kbit/s (Software configurable)	
Node address	1 127 (Software configurable)	
Termination switchable	Software configurable	
LSS Protocol	CIA LSS protocol DS305 Global command support for node address and baud rate. Selective commands via attributes of the identity object	

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## **CANopen**

#### **General information about CANopen**

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.02 . In addition, device-specific profiles like the encoder profile DS406 V3.2 are available.

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CAN-Bus. When switching the device on, all parameters, which have been saved on a flash memory to protect them against power failure, are loaded again.

The following output values may be combined in a freely variable way as PDO (PDO mapping): **position**, **speed** as well as the **status of the working area**.

The encoders are available with a connector or a cable connection.

The device address and baud rate can be set/modified by means of the software.

The two-colour LED located on the back indicates the operating or fault status of the CAN bus, as well as the status of the internal diagnostics.

#### **CANopen Communication Profile DS301 V4.02**

Among others, the following functionality is integrated. Class C2 functionality:

- NMT Slave
- Heartbeat Protocol
- · Identity Object
- · Error Behaviour Object
- Variable PDO Mapping self-start programmable (Power on to operational), 3 Sending PDO's
- · Node address, baud rate and CANbus / Programmable termination

## CANopen Encoder Profile DS406 V3.2

The following parameters can be programmed:

- Event mode
- 1 work area with upper and lower limit and the corresponding output states
- Variable PDO mapping for position, speed, work area status
- · Extended failure management for position sensing
- User interface with visual display of bus and failure status 1 LED two colours
- Customer-specific memory 16 Bytes
- · Customer-specific protocol

"Watchdog controlled" device

### LSS Layer Setting Services DS305 V2.0

- . Global support of Node-ID and baud rate
- Selective protocol via identity object (1018h)

#### **CAN** bus connection

The CANopen encoders are equipped with a Bus trunk line in various lengths and can be terminated in the device.

The devices do not have an integrated T-coupler nor they are looped internally and must therefore only be used as end devices.

If possible, drop lines should be avoided, as in principle they lead to signal reflections. As a rule the reflections caused by the drop lines are not critical, if they have completely decayed before the point in time when the scanning

The sum of all the drop lines should not, for a particular baud rate, exceed the maximum length  ${\sf Lu.}$ 

Lu < 5 m cable length for 125 Kbit

Lu < 2 m cable length for 250 Kbit

Lu < 1 m cable length for 1 Mbit

When used as a drop line, the termination resistor should not be activated.

For a network with 3 encoders and 250 Kbit the maximum length of the drop line/

## Terminal assignment

Signal:	+U <sub>B</sub>	0 V	CAN GND	CAN High	CAN Low
Cable colour:	BN	WH	GY	GN	YE

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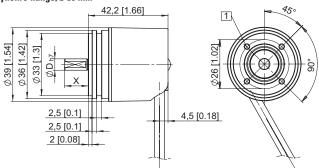
# Compact, optical

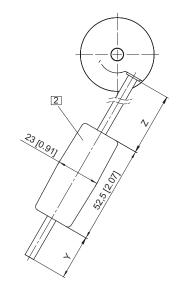
Sendix F3668 / F3688 (Shaft / Hollow shaft)

**CANopen** 

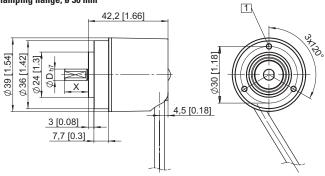
## **Dimensions shaft version:**

## Synchro flange, ø 36 mm





### Clamping flange, ø 36 mm



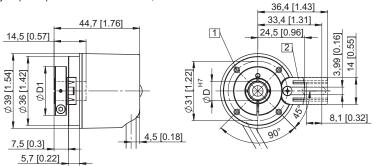
- 1 M3, 6 [0.24] deep
- 2 Battery (in the cable)

Υ	Z
1 m	150 mm
5 m	150 mm
	•

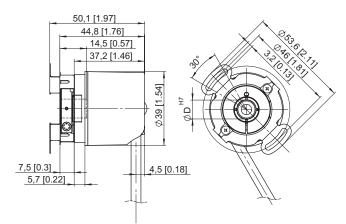
#### **Dimensions hollow shaft version:**

## With torque stop, short, ø 36 mm

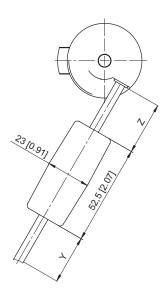
(Long torque stop version is shown dashed)



# With stator coupling, ø 36 mm



- 1 M2.5. 5 [0.2] deep
- 2 Torque stop slot Recommendation: cylindrical pin DIN 7, ø 4 mm
- 3 Battery (in the cable)



Hollow shaft acc. to order code	D1
1	ø 24 mm
2	ø 24 mm
3	ø 25.5 mm
4	ø 25.5 mm

Y	Z
1 m	150 mm
5 m	150 mm

Insertion depth for blind hollow shaft 14,5 mm

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