



Real energy measurement of two equal solar panels (fixed and motorized)
Three equal solar panels were exposed to the sun and the converted electrical power was measured.
Test conditions: <u>Solar panels (all)</u>: 0.75 kWp (producer spec, at AN 1.5), <u>Date</u>; July 2010
Time: 4:00 to 20:00 (sun time), <u>Geo. latitude</u>: 46°N, <u>Weather conditions</u>; sunny
Results: <u>Average energy of fixed</u>; 3762 Wh, <u>Average energy of motorized</u>; 6093 Wh,
<u>Mota</u>: sum of motor energy consumption through all day at full load is 17.52Wh or 0.29%
of all collected energy. <u>Efficiency of the motorized panel</u>; 161,5%

Number of turning axis	Dual-Axis
Hour Angle Limit	100°, software and hardware limit
Elevation angle	15 - 90°, adjustable start
Type of hour-angle engine	Linear Motor SM4S520M2 with stroke of 520mm
Type of elevation shaft and stroke	Linear motor SM4S520M2 with stroke of 520mm
Hour-angle shaft diameter and length	Ø48 mm, L=1450mm (steel)
Turning speed of hour angle shaft	0,039 - 0,063 °/s at no load, see graph
Turning speed of elevation shaft	0,052 - 0,062 °/s at no load, see graph
Max. dynamic torque of the hour-angle shaft	200 Nm - 330 Nm depend from HA, see graph
Max. dynamic torque of elevation shaft	330 Nm - 400 Nm depend from EA, see graph
Destructive torque of the hour-angle shaft	750Nm-1250Nm, depend from HA, see graph
Destructive torque of elevation shaft	1250Nm-1500Nm, depend from HA, see graph
Backstructure size	2 pcs of 1000mm (H) & 2 pcs of 3000mm (V)
Type of backstructure clamp	Toothed scissors gripers - 12 pcs
Tube diameter for mounting	Ø60 - 68 mm (not included with kit)
Max. dimensions of a solar panel	3 pieces of 0.99 m x 1.95 m in total 5.8 m2
Max. weight of a solar panel	3 pcs per 30 kg
Estimated service life	5.000 rotations of 200° or 10 years
Positioning System Data	
Tracking accuracy	<0.5° (optionally <0.1° ***)
Operating Protocol	TdAPS (Time derived Astronomical Positioning System)
Type of positioner	Servo driver positioner with TdAPS arc logic function calc.
Type of timer	GMT clock with EOT and calendar
Type of application program for supervision and setting	Solar tracking system monitor via web site
Setting and changing data via PC	Yes, It can be setup 1000 parameters
Monitoring possibility via PC	Yes, It can be monitored 1000 parameters
Turned on the position sent from PC	Yes, it turn on position sent from PC, also all other setting can be commanded with string sent from PC
Communication Data	
Type of communication interface	USB interface
Networking solution for control from centre	CAN BUS, RS485
Firmware - Software	
Upgrading possibility via PC	Yes, firmware via PC with help of web wizard
Electrical Data	103, minute viol o minute of neo vices
	In the terms of
Motor Power Supply	24 VDC ± 10% (2A current capacity)
Motor Power Supply Backup battery	Backup for timer, position and data
Motor Power Supply Backup battery Turning time interval	Backup for timer, position and data Imin 15min.
Motor Power Supply Backup battery Turning time interval Max. consumption during the operation of the hour-angle shaft	Backup for timer, position and data Imin 15min. 500mA (a) 330Nm, see graph
Motor Power Supply Backup battery Turning time interval Max. consumption during the operation of the hour-angle shaft Max. Current of elevation shaft	Backup for timer, position and data Imin 15min. 500mA @ 330Nm, see graph 500mA @ 400Nm, see graph
Motor Power Supply Backup battery Turning time interval Max. consumption during the operation of the hour-angle shaft Max. Current of elevation shaft Standby consumption (when is not moving)	Backup for timer, position and data Imin15min. 500mA (a) 330Nm, see graph 500mA (a) 400Nm, see graph 20mA ± 25% (a) 24V
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